

1. 8 points Apply the Gram-Schmidt process to the vectors  $\vec{v}_1 = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$ ,  $\vec{v}_2 = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$ , and write the result in the form  $A = Q \cdot R$ .

$$r_{11} = \|\vec{v}_1\| = \sqrt{16 + 9} = 5$$

$$\vec{u}_1 = \frac{1}{r_{11}} \vec{v}_1 = \frac{1}{5} \begin{bmatrix} 4 \\ 3 \end{bmatrix}$$

$$r_{12} = \vec{u}_1 \cdot \vec{v}_2 = \frac{1}{5} \begin{bmatrix} 4 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \frac{2}{5}$$

$$\vec{v}_2^\perp = \vec{v}_2 - r_{12} \vec{u}_1 = \begin{bmatrix} -1 \\ 2 \end{bmatrix} - \frac{2}{5} \cdot \frac{1}{5} \begin{bmatrix} 4 \\ 3 \end{bmatrix} = \frac{11}{25} \begin{bmatrix} -3 \\ 4 \end{bmatrix}$$

$$r_{22} = \|\vec{v}_2^\perp\| = \frac{11}{25} \sqrt{9 + 16} = \frac{11}{5}$$

$$\vec{u}_2 = \frac{1}{r_{22}} \vec{v}_2^\perp = \frac{5}{11} \cdot \frac{11}{25} \begin{bmatrix} -3 \\ 4 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} -3 \\ 4 \end{bmatrix}$$

$$A = Q \cdot R$$

$$\begin{bmatrix} \vec{v}_1 & \vec{v}_2 \end{bmatrix} = \begin{bmatrix} \vec{u}_1 & \vec{u}_2 \end{bmatrix} \cdot \begin{bmatrix} r_{11} & r_{12} \\ 0 & r_{22} \end{bmatrix}$$

$$\begin{bmatrix} 4 & -1 \\ 3 & 2 \end{bmatrix} = \begin{bmatrix} 4/5 & -3/5 \\ 3/5 & 4/5 \end{bmatrix} \cdot \begin{bmatrix} 5 & 2/5 \\ 0 & 11/5 \end{bmatrix}$$

2. 6 points Consider the vectors  $\vec{v} = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$  and  $\vec{w} = \begin{bmatrix} -2 \\ 5 \\ 5 \end{bmatrix}$ .

(a) Find the matrix of the orthogonal projection onto the line  $L$  in  $\mathbb{R}^3$  spanned by  $\vec{v}$ .

$$\vec{u} = \frac{1}{\|\vec{v}\|} \vec{v} = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$$

$$A = \vec{u} \cdot \vec{u}^\top = \frac{1}{\sqrt{6}} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} \cdot \frac{1}{\sqrt{6}} [1 \quad -1 \quad 2] = \frac{1}{6} \begin{bmatrix} 1 & -1 & 2 \\ -1 & 1 & -2 \\ 2 & -2 & 4 \end{bmatrix}$$

(b) Find the projection of  $\vec{w}$  onto the line  $L$ .

$$\text{proj}_L(\vec{w}) = A\vec{w} = \frac{1}{6} \begin{bmatrix} 1 & -1 & 2 \\ -1 & 1 & -2 \\ 2 & -2 & 4 \end{bmatrix} \cdot \begin{bmatrix} -2 \\ 5 \\ 5 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

3. 5 points Is there an orthogonal transformation  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  such that

$$T \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} -3 \\ 1 \end{bmatrix} \quad \text{and} \quad T \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} -2 \\ -1 \end{bmatrix}?$$

Justify your answer, one way or the other.

An orthogonal transformation must preserve dot products of vectors:

$$T\vec{x} \cdot T\vec{y} = \vec{x} \cdot \vec{y}, \quad \text{for all vectors } \vec{x}, \vec{y}.$$

In this situation, though:

$$\begin{aligned} T \begin{bmatrix} 1 \\ 3 \end{bmatrix} \cdot T \begin{bmatrix} 1 \\ 2 \end{bmatrix} &= \begin{bmatrix} -3 \\ 1 \end{bmatrix} \cdot \begin{bmatrix} -2 \\ -1 \end{bmatrix} = 6 - 1 = 5 \\ \begin{bmatrix} 1 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 1 \\ 2 \end{bmatrix} &= 1 + 6 = 7 \end{aligned}$$

Thus, there is no such orthogonal transformation  $T$ .

4. 6 points Let  $A$  be an arbitrary  $n \times n$  matrix. and let  $Q$  be an orthogonal  $n \times n$  matrix. For each of the following questions, answer: “Yes, always,” or “Sometimes yes, sometimes not,” or “No, never.” Justify your answer, as much as possible.

- (a) The matrix  $AA^T$  is symmetric.

Yes, always:  $(AA^T)^T = (A^T)^T A^T = AA^T$

- (b) The matrix  $AA^T$  is invertible.

Sometimes yes, for example, when  $A$  is the identity matrix, and sometimes not, for example, when  $A$  is the zero matrix.

- (c) The matrix  $AA^T$  is orthogonal.

Sometimes yes, for example, when  $A$  is the identity matrix, and sometimes not, for example, when  $A$  is the zero matrix.

- (d) The matrix  $Q^T$  is symmetric.

Sometimes yes, for example, when  $Q$  is the identity matrix, and sometimes not, for example, when  $Q = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ .

- (e) The matrix  $Q^T$  is invertible.

Yes, always:  $QQ^T = I_n$ , so  $Q$  is the inverse matrix to  $Q^T$ .

- (f) The matrix  $Q^T$  is orthogonal.

Yes, always:  $Q^T(Q^T)^T = Q^T Q = I_n$ .