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Motivation

Abstract Snak Graphs

Relation to Cluster Algebra

Band Graphs and Future Directions

On surface cluster algebras: Band and snake graph calculus

Ilke Canakci¹ Ralf Schiffler¹

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Background

- Cluster algebras, introduced by **Fomin and Zelevinsky** in [FZ1] form a class of combinatorially defined commutative algebras, and the set of **generators** of a cluster algebra, **cluster variables**, is obtained by an iterative process.
 - with boundary that has finitely many marked points.

- Guster variables are in bijection with certain curves [FST], called arcs.
- The authors in [MSW] associates a connected graph, called the snake graph to each arc in the surface to obtain a direct formula for cluster variables of surface cluster algebras.

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Let $\mathcal{A}(S, M)$ cluster algebra associated to a surface (S, M).

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Question

"How much can we recover from snake graphs themselves?" In particular,

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- (ii) G_i and G_j have no edge in common whenever $|i j| \ge 2$.
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Example



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Notation

• $G = (G_1, G_2, \dots, G_d)$ • $G[i, i+1] = (G_0, G_0, i_0, \dots, G_{n+1})$ • We denote by e_i the interior edge between the tiles G_i and G_{i+1} .

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 \mathcal{G}_2

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• $\mathcal{G} = (G_1, G_2, \ldots, G_d)$

G

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Sign Function

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Example A sign function on \mathcal{G}_1 and \mathcal{G}_2

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Example

A sign function on \mathcal{G}_1 and \mathcal{G}_2



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Abstract Snake Graphs

Sign Function

Definition

A sign function f on a snake graph G is a map f from the set of edges of \mathcal{G} to $\{+,-\}$ such that on every tile in \mathcal{G} the north and the west edge have the same sign, the south and the east edge have the same sign and the sign on the north edge is opposite to the sign on the south edge.

Example



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Motivation

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Definition

We say that \mathcal{G}_1 and \mathcal{G}_2 cross in a local overlap \mathcal{G} if one of the following conditions hold.



Example

 \mathcal{G}_1 and \mathcal{G}_2 cross at the overlap \mathcal{G} .



Crossing

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Crossing

Definition

We say that \mathcal{G}_1 and \mathcal{G}_2 cross in a local overlap \mathcal{G} if one of the following conditions hold.

- $f_1(e_{s-1}) = -f_1(e_t)$ if s > 1, t < d
- $f_1(e_{s-1}) = f_2(e_{t'}')$ if s > 1, t < d, s' = 1, t' < d'

Example



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Abstract Snake Graphs

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Example



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Example: Resolution $\operatorname{Res}_{\mathcal{G}}(\mathcal{G}_1, \mathcal{G}_2)$



 \mathcal{G}_2

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Example: Resolution $\operatorname{Res}_{\mathcal{G}}(\mathcal{G}_1, \mathcal{G}_2)$



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Example: Resolution Res $_{\mathcal{G}}(\mathcal{G}_1, \mathcal{G}_2)$





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Example: Resolution $\operatorname{Res}_{\mathcal{G}}(\mathcal{G}_1, \mathcal{G}_2)$





 \mathcal{G}_4

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Example: Resolution $\operatorname{Res}_{\mathcal{G}}(\mathcal{G}_1, \mathcal{G}_2)$





 \mathcal{G}_4

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 \mathcal{G}_2

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Example: Resolution (Continued)



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Example: Resolution (Continued)



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Example: Resolution (Continued)



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Motivation

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Resolution: Definition

Assumption: We will assume that s > 1, t < d, s' = 1 and t' < d'. For all other cases, see [CS].

Ne define four connected subgraphs as follows.

- $G_3 = G_1[1, t] \cup G_2[t' + 1, d'],$
- $\mathcal{G}_4 = \mathcal{G}_2[1,t'] \cup \mathcal{G}_1[t+1,d],$
- on the interior edge of tiles $s \sim 1$ and s_1
- $\begin{aligned} &\mathcal{G}_{0} := \mathcal{G}_{0}[d^{2}, t^{2} \mapsto 1] \cup \mathcal{G}_{1}[t \mapsto 1, d] \text{ where the two subgraphs are glued } \\ &\text{ along the south } \mathcal{G}_{0,1} \text{ and the north of } \mathcal{G}_{0,2} \cup f^{2} \mathcal{G}_{0,2} \text{ is north of } \mathcal{G}_{1} \text{ in } \mathcal{G}_{0,2} \text{ or } \mathcal{G}_{0,2} \text{ o$

Definition

The resolution of the crossing of \mathcal{G}_1 and \mathcal{G}_2 in \mathcal{G} is defined to be $(\mathcal{G}_3 \sqcup \mathcal{G}_4, \mathcal{G}_5 \sqcup \mathcal{G}_6)$ and is denoted by Res $_{\mathcal{G}}(\mathcal{G}_1, \mathcal{G}_2)$.

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- G₅ = G₁[1, k] where k < s − 1 is the largest integer such that the sign on the interior edge between tiles k and k + 1 is the same as the sign on the interior edge of tiles s − 1 and s,
- $\mathcal{G}_6 = \overline{\mathcal{G}}_2[d', t'+1] \cup \mathcal{G}_1[t+1, d]$ where the two subgraphs are glued along the south G_{t+1} and the north of $G'_{t'+1}$ if G_{t+1} is north of G_t in \mathcal{G}_1 .

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Motivation

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Band Graphs and Future Directions

Bijection of Perfect Matchings

Definition

A **perfect matching** P of a graph G is a subset of the set of edges of G such that each vertex of G is incident to exactly one edge in P.

Let Match(G) denote the set of all perfect matchings of the graph G and graph G and $Match(Res_{\mathcal{G}}(G_1, G_2)) =: Match(G_2 \cup G_4) \cup Match(G_2 \cup G_6)$.

Theorem (CS) Let G_1, G_2 be two snake graphs. Then there is a bijection

 $\mathsf{Match}\,(\mathcal{G}_1 \sqcup \mathcal{G}_2) \longrightarrow \mathsf{Match}\,(\mathsf{Res}_{\,\mathcal{G}}(\mathcal{G}_1, \mathcal{G}_2))$

ote that we construct the bijection map and its inverse map

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 Note that we construct the bijection map and its inverse map explicitly.

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Band and snake graph calculus

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Motivation

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Band Graphs and Future Directions

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Surface Example



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Relation to Cluster Algebras

Let γ_1 and γ_2 be two arcs and \mathcal{G}_1 and \mathcal{G}_2 their corresponding snake graphs.

Theorem (CS

 γ_1 and γ_2 cross if and only if \mathcal{G}_1 and \mathcal{G}_2 cross.

Theorem (CS)

If γ_1 and γ_2 cross, then the snake graphs of the four arcs obtained by **smoothing the crossing** are given by the **resolution** $\operatorname{Res}_{\mathcal{G}}(\mathcal{G}_1, \mathcal{G}_2)$ of the crossing of the snake graphs \mathcal{G}_1 and \mathcal{G}_2 at the overlap \mathcal{G} .

Remark

We do not assume that γ_1 and γ_2 cross only once. If the arcs cross multiple times the theorem can be used to resolve any of the crossings.

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Theorem (CS)

If γ_1 and γ_2 cross, then the snake graphs of the four arcs obtained by **smoothing the crossing** are given by the **resolution** $\operatorname{Res}_{\mathcal{G}}(\mathcal{G}_1, \mathcal{G}_2)$ of the crossing of the snake graphs \mathcal{G}_1 and \mathcal{G}_2 at the overlap \mathcal{G} .

Remark

We do not assume that γ_1 and γ_2 cross only once. If the arcs cross multiple times the theorem can be used to resolve any of the crossings.

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Skein Relations

As a corollary we obtain a new proof of the skein relations [MW]. Corollary (CS) $% \left(\left(CS\right) \right) =0$

Let γ_1 and γ_2 be two arcs which cross and let (γ_3, γ_4) and (γ_5, γ_6) be the two pairs of arcs obtained by smoothing the crossing. Then

$$x_{\gamma_1}x_{\gamma_2} = x_{\gamma_3}x_{\gamma_4} + y(ilde{\mathcal{G}})x_{\gamma_5}x_{\gamma_6}$$

where $\tilde{\mathcal{G}}$ is the closure of the overlap \mathcal{G} .

Remark

- Note that Musiker and Williams in [MW] use hyperbolic geometry to prove the skein relations.
- Our proof is purely combinatorial. The key ingredient to our proof is Theorem 12 where we show the bijection between the periest matchings.

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Band Graphs

- I am currently working on extending our combinatorial formulas to **band graphs** associated to *closed loops* in a surface, see [MSW2].
- Closed loops appear naturally in the process of smoothing crossings. Consider the following example.

Example

In this example we resolve two crossings of the following arcs.

Question: Is this construction straightforward? Answer: No!

The difficulty here is to show the 'skein relations' for self-crossing

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Thank you!

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Band Graphs and Future Directions I. Canakci, R. Schiffler *Snake graph calculus and cluster algebras from surfaces*, to appear in *Journal of Algebra*, preprint available at arxiv:1209.4617v1.

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